Analysis and modeling of Computational Performance

Lecture 10

Single node performance optimization

- Software optimization can have several goals:
 - minimization of execution time
 - the only one we are interested in, further called just optimization
 - minimization of memory footprint
 - other requirements, often depending on the particular software type or domain of application
- Optimization can be performed by different means at different stages of software development
 - by properly choosing algorithms and data structures while designing codes
 - depends on the domain of application
 - by proper implementation at the stage of source code creation
 - the main concern today is exploitation of parallel capabilities
 - even scalable software should have high single node performance
 - by using optimizing compiler
 - by the use of hardware designed for performance

- Software optimization is often blamed for being an obstacle for proper code development
 - Donald Knuth: ""Premature optimization is the root of all evil"
 - but the full quote includes "The real problem is that programmers have spent far too much time worrying about efficiency in the wrong places and at the wrong times; ..."
 - Performance optimization have to be done for the code that works
 - however, in order to give optimization a chance to improve the performance, the code has to be designed from the beginning with the future performance optimization in mind
 - Often employed strategy
 - predict the places most important from the performance point of view
 - separate the related code, create working version of the program
 - perform optimization, by removing "bottlenecks"
 - > bottleneck is a place that cause performance degradation for a particular code or even particular case of input data

Top-Down Method for Performance Analysis

One Bottlenecks Hierarchy*



- The prediction of places most important from the performance point of view can be based on the analysis of the number of instructions and memory accesses done in a given part of the code
 - the parts of the code with the highest percentage of expected execution time are called "hot spots"
 - optimizing "hot spots" may be the most effective way for performance improvement
 - "hot spots" often become performance "bottlenecks"
 - it is also possible that a bottleneck appears in a place where relatively few operations are performed but these operations are (or become in certain circumstances) extremely slow
 - * e.g. swapping or other secondary storage (hard disk or SSD) access, slow network connection, etc.
 - we will be mainly concerned with "hot spot" optimization, but will keep in mind that code profiling and bottleneck discovery should be the first step in optimization for a particular code

- The optimization should concern parts of the code most important from the performance point of view
 - "hot spots" can be identified through algorithm and source code analysis
 - "bottlenecks" can be found by profiling
- After separating the code related to the performance, different actions can be performed:
 - a proper high performance library can be found that provides functions necessary for code implementation
 - e.g. many linear algebra packages, with LAPACK being a prominent example, are successfully used in numerous programs
 - using libraries creates dependencies that may become problematic during code evolution
 - optimization can be performed for the code
 - the optimization usually depends on target execution environment and hardware, creating less portable code

- ➔ How to optimize a part of the code:
 - use optimizing compiler
 - perform manual optimization
 - contemporary optimizing compilers are doing their job very well
 - it is difficult to obtain by changing the source the same effect as by the use of an optimizing compiler
 - without optimization options compilers often produce unnecessarily slow code (e.g. for debugging purposes)
 - the best way for manual optimization is to apply specific techniques that help compilers to produce more effective code
 - allow for reducing the number of operations, effectively using different instruction pipelines, removing dependencies, choosing proper functions and instructions, vectorizing code, optimally use memory hierarchy
 - use a different programming language, designed for performance
 - eventually employ assembler language

Single node performance optimization

- Summary of techniques, important points, pitfalls to avoid
 - increase data locality and optimize memory access patterns
 - for reducing the number of memory accesses and better cache utilization
 - > use e.g. cache blocking, register blocking
 - > minimize the number of TLB misses
 - for better use of NUMA memories
 - > use proper data placement together with thread affinity control
 - avoid memory contention (mapping different data to the same cache line, cache block, memory bank, etc.)
 - array sizes being the power of two
 - use padding
 - avoid false sharing
 - reduce pipeline stalls, caused e.g. by
 - data dependencies
 - indirect addressing
 - function calls, conditional statements (especially inside loops)

Single node performance optimization

- Summary of techniques, important points, pitfalls to avoid
 - allow optimizing compilers to work efficiently
 - remove aliases
 - inform compilers using suitable options or directives
 - allow for vectorization (remove dependencies)
 - use special memory allocation with proper alignment
 - perform classical optimizations that are not done by the compiler
 - reduce the number of operations in the algorithm, increase locality, etc.
 - especially when the task is too complex for the compiler
 - reduce system overhead when possible
 - do not allow for major page faults
 - allow hardware to effectively employ branch prediction, hardware prefetching, hardware multithreading, out-of-order execution, etc.
 - when necessary use software prefetching
 - use compiler *intrinsics* or assembly code

- Steps in practical software optimization process
 - choose proper algorithm (with future performance in mind)
 - implement for functional requirements
 - and possibly some, other than performance, non-functional requirements (safety, security, reliability etc.)
 - compile with proper optimization options switched on and create execution profile and identify performance bottlenecks
 - use high performance library routines for bottlenecks
 - if exist and their use does not interfere with other code development goals and limitations (e.g. required independence of external libraries)
 - manually optimize parts of the code related to performance
 - always check the effects of modifications using different compilers and compiler options – inspect assembler and test execution time
 - use different language for kernel implementation
 - eventually employ assembler intrinsics or write assembly code
 - test the final performance use profilers, hardware counters, etc.
 - compare with the peak performance of the executing hardware